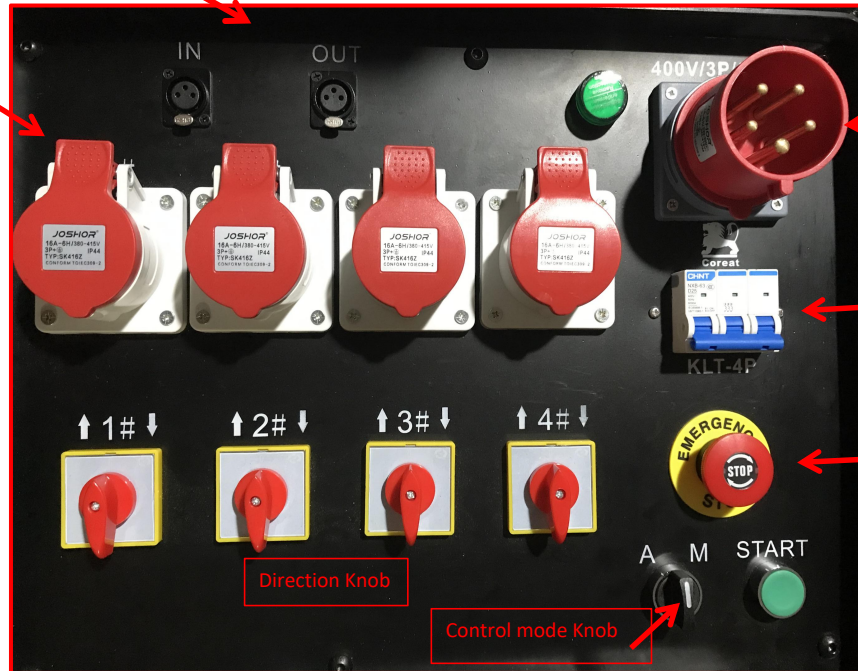




Using 3pin signal cable to connect with other controller with the same function, then can realized master-slave function. Ig. 2units of 4 way controller= 8units control.

hoist to controller cable plug in



Spin power input

Power supply switch

Emergency Stop

Direction Knob

Control mode Knob



A=Automatic
M=Manual
Start=Jog
M+Start= Manual Jog



switch the direction knob, switch the control mode knob to M. Press the Start button can control the hoist running. Unpress the button then would stop running.



Switch direction knob, switch the control mode knob to A, the hoist/hoists would go continuously, won't be stop until you switch it to neutral or press Emergency button.

